

Size Concepts

Size Tool: The Size tool is a toleranced nominal dimension. It defines a tolerance zone consisting of the space between a "Maximum Material Condition boundary" of perfect form and a non-intersecting, "Least Material Condition boundary" of not necessarily perfect form, which is the surface swept by the "Least Material Condition Sphere".

Size control concepts:

- (1) the **Maximum Material Condition Size** = the extreme permissible size of the feature at Maximum Material Condition
- (2) the **Least Material Condition Size** = the extreme permissible local size of the feature at Least Material Condition,
- (3) the **Unconstrained Actual Mating Size** = the size of the Unconstrained Actual Mating Envelope of an actual feature,

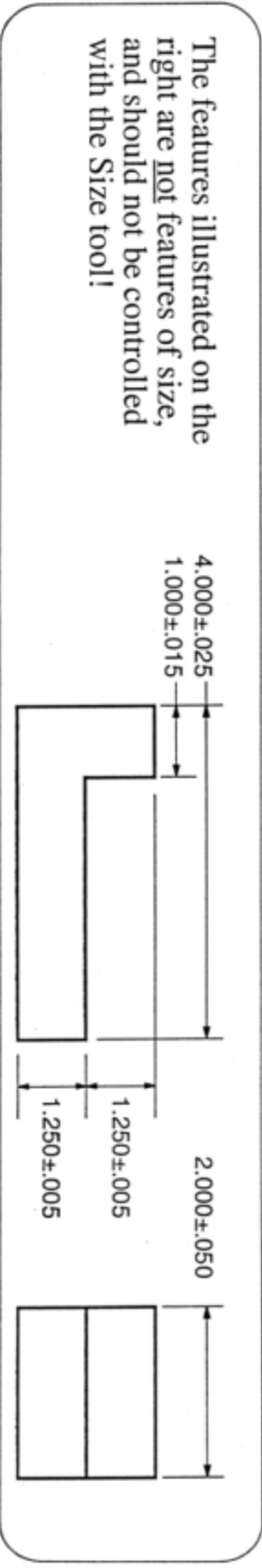
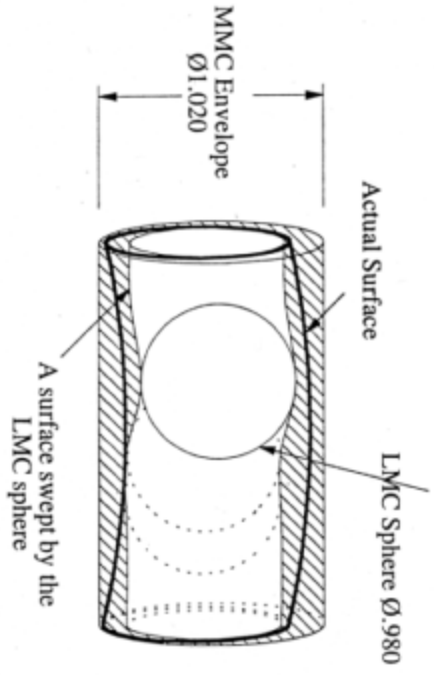


(4) the **Orientation Constrained Actual Mating Size** = the size of the Orientation Constrained Actual Mating Envelope of an actual feature,

(5) the **Location Constrained Actual Mating Size** = the size of the Location Constrained Actual Mating Envelope of an actual feature,

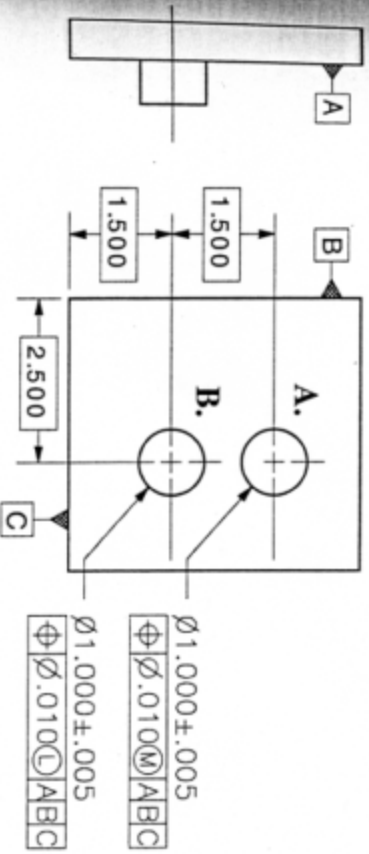
(6) the **Actual Local Size** = the diameter of the maximum inscribed or minimum circumscribed sphere (opposed point distance) at any location in an actual feature,

(7) the **LMC Actual Local Size** = the extreme LMC value of the **Actual Local Size** of a feature.



Virtual and Resultant Condition

Material Free & Filled Boundaries



Definition: The terms Virtual and Resultant Condition refer to the "size" of the Material Free and Material Filled Boundaries of a feature, as a result of the collective effects of the tolerances imposed on its size, form, orientation and location.

Application: The "Material Free Boundary" of the Considered Feature establishes the extreme limit of the "Material Free Boundary" of the mating feature. The concept thus serves to ensure assemblability.

Note: The terms "Virtual" and "Resultant" condition are poorly defined in the ASME Y14.5M 1994 standard (§1.3.23 p. 3 and § 1.3.37 p. 4) recommending substitution by the terms "Material Free Boundary" and "Material Filled Boundary" as highlighted below.

A. Internal Cylinder

Material Free Boundary (Virtual Condition Boundary / Inner Boundary / In Air Boundary)

$\varnothing 1.000$	Material Filled Zone
Size Tol. -.005	
Pos. Tol. -.010	
$\varnothing 0.985$	Material Free Zone
$\varnothing 1.000$	LMC Bore
Size Tol. +.005	
Pos. Tol. +.010	
Pos. Bonus +.010	Position Tolerance Zone at LMC
$\varnothing 1.025$	Position Tolerance Zone at MMC

Material Filled Boundary (Resultant Condition Boundary / Outer Boundary / In Material Boundary)

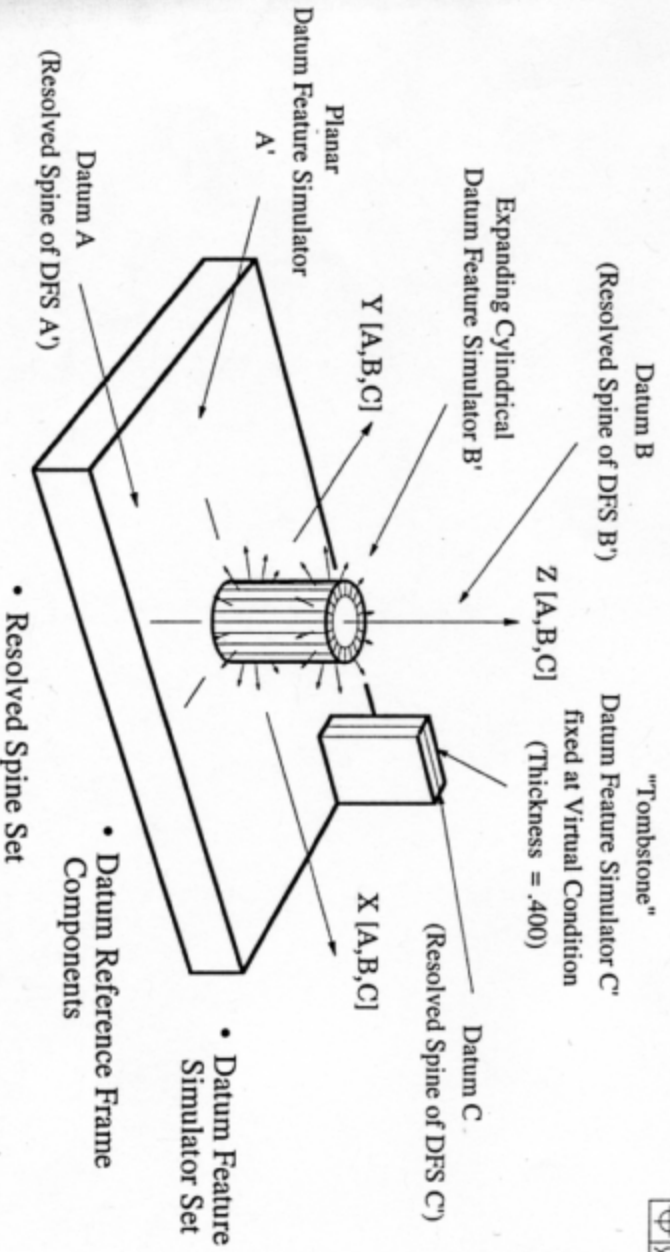
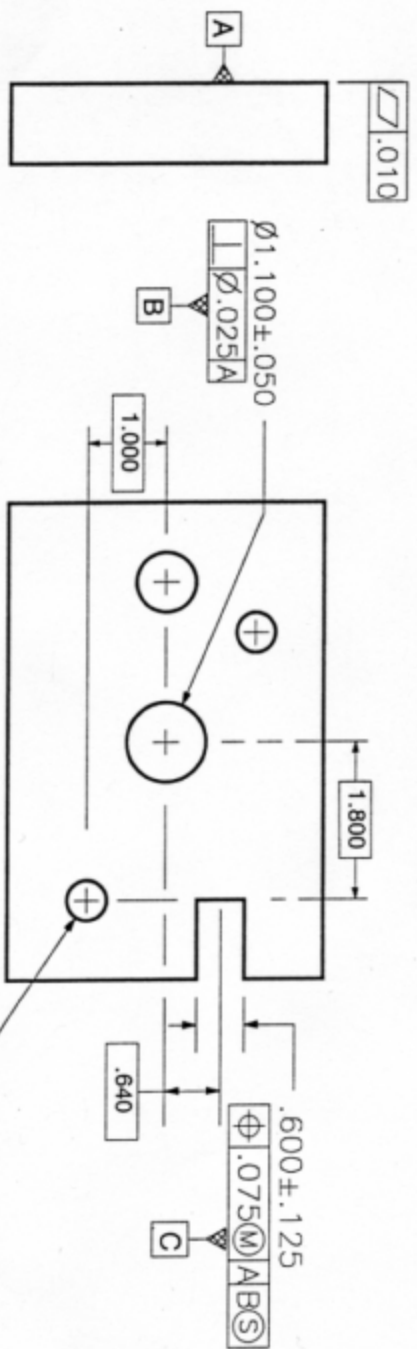
B. External Cylinder

Material Filled Boundary (Virtual Condition Boundary / Inner Boundary / In Material Boundary)

$\varnothing 1.000$	Material Free Zone
Size Tol. -.005	
Pos. Tol. -.010	
$\varnothing 0.985$	Material Filled Zone
$\varnothing 1.000$	MMC Boss
Size Tol. +.005	
Pos. Tol. +.010	Position Tolerance Zone at MMC
Pos. Bonus +.010	Position Tolerance Zone at LMC

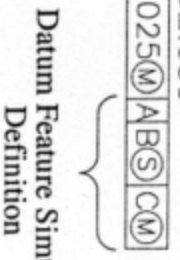
Material Free Boundary (Resultant Condition Boundary / Outer Boundary / In Air Boundary)

Datum Reference Frame Construction Process Introduction



Datums are the Resolved Spines of Datum Feature Simulators

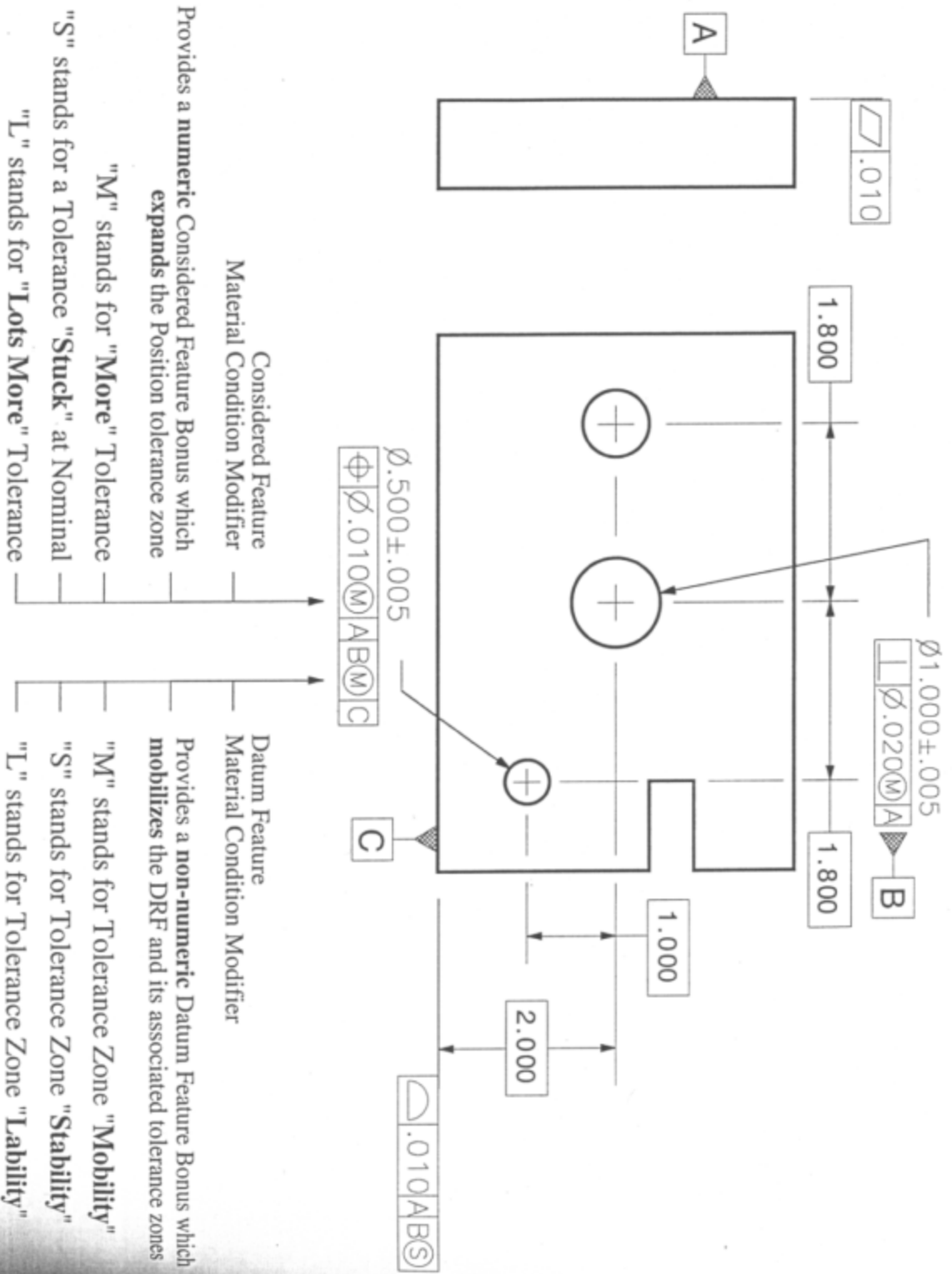
- Datum Feature Simulator Set
- Datum Reference Frame Components
- Resolved Spine Set



The Sullivan - Tandler Degrees of Constraint Matrix

	P+Y	R	X	Y	Z
A	X	--	--	--	X
B	(X)	--	X	X	--
C	(X)	X	--	(X)	--

Tolerance Zone Expansion & Mobilization



Provides a **numeric** Considered Feature Bonus which expands the Position tolerance zone

Considered Feature Material Condition Modifier

Provides a **non-numeric** Datum Feature Bonus which mobilizes the DRF and its associated tolerance zones

Datum Feature Material Condition Modifier

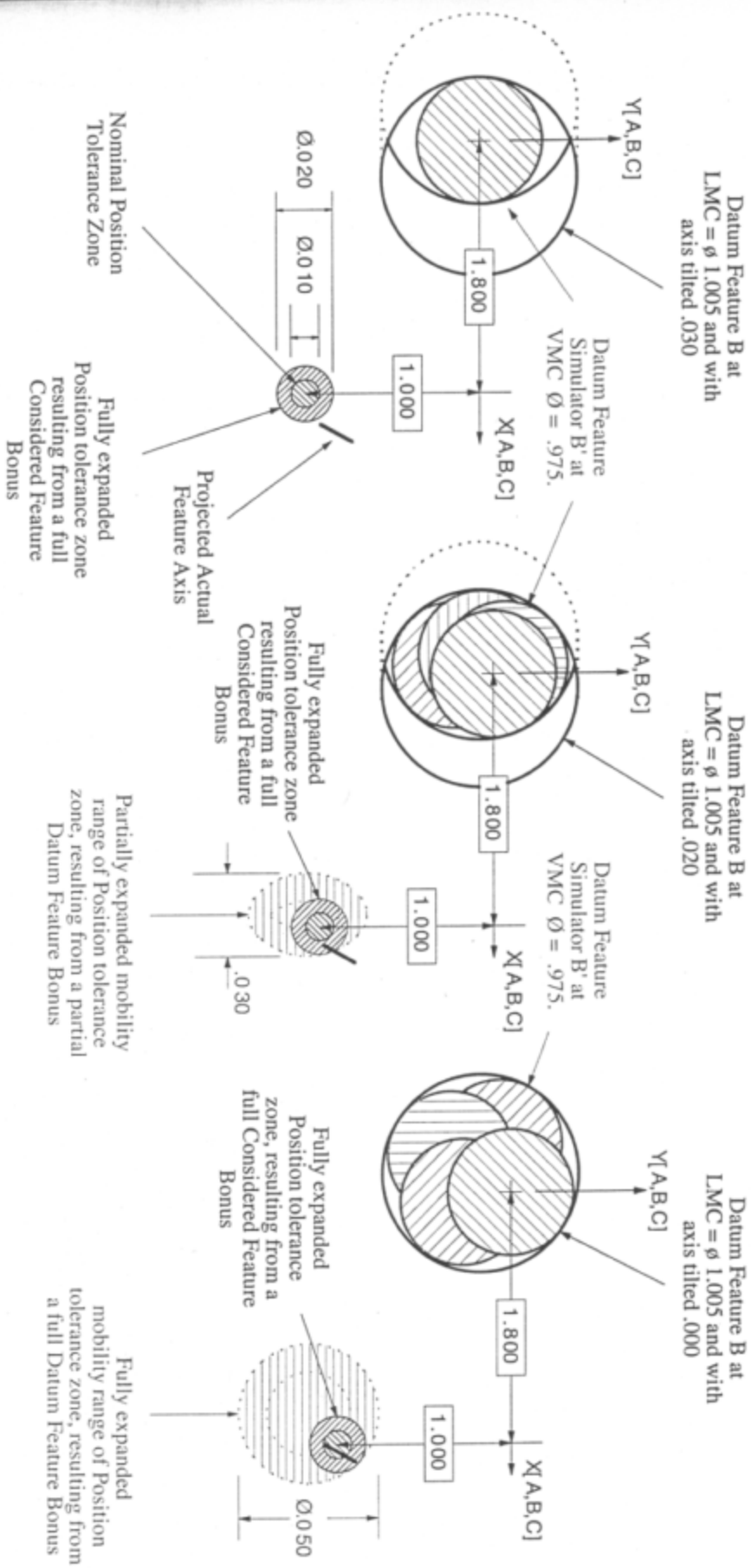
"M" stands for "**More**" Tolerance
 "S" stands for a Tolerance "**Stuck**" at Nominal
 "L" stands for "**Lots More**" Tolerance

"M" stands for Tolerance Zone "**Mobility**"
 "S" stands for Tolerance Zone "**Stability**"
 "L" stands for Tolerance Zone "**Liability**"

Tolerance Zone Expansion & Mobilization

As the diameter of the Considered Feature departs from MMC toward LMC, its Position tolerance zone expands due to the associated MMC modifier. Furthermore, as Datum Feature B departs from its Maximum Material Condition and becomes ever more perpendicular to Datum A, Datum Reference Frame AB(M)C and the attached Position tolerance zone of the Considered Feature become ever more free to move in both X and Y. The illustration below shows the effects on the size and mobility of the Considered Feature's Position tolerance zone as a function of (1) changes in the Material Condition of the

Considered Feature and (2) changes in the Orientation of Datum Feature B with B fixed at LMC. Note that no rotational mobility accompanies the Material Condition induced translational mobility of the DRF, because the Datum Feature Simulator representing Datum Feature C is traditionally "interpreted" to be a spring loaded, floating fence. Note that the full Datum Feature Bonus is required to permit the fully expanded Position tolerance zone to move far enough to accommodate the actual axis of the Considered Feature!

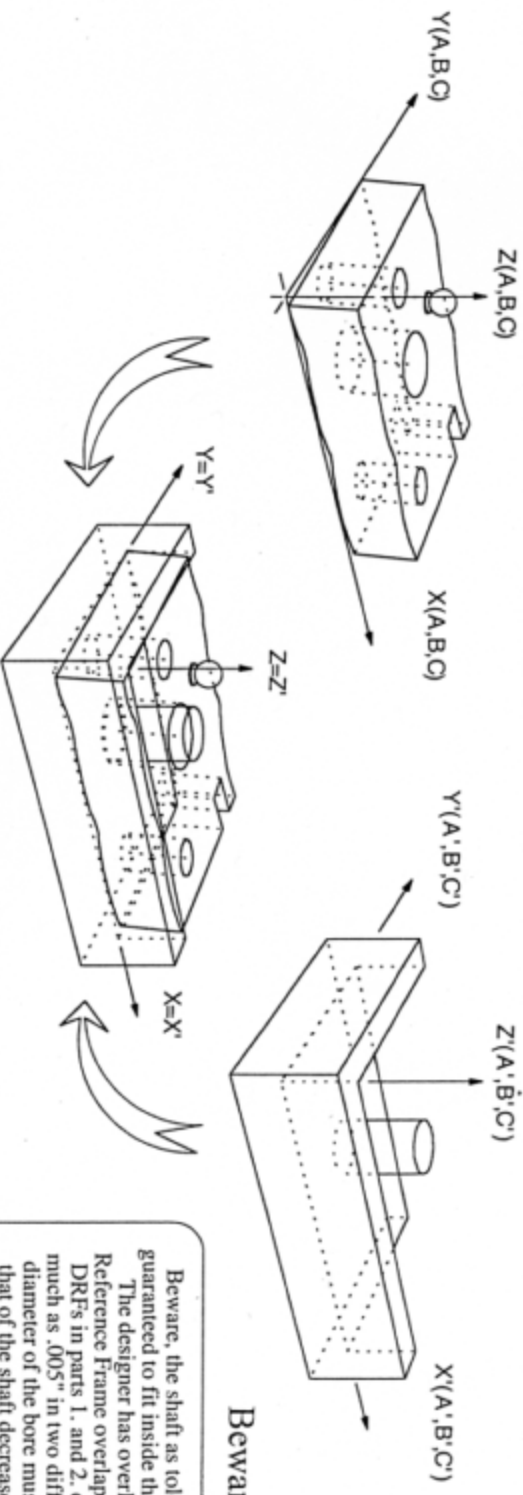
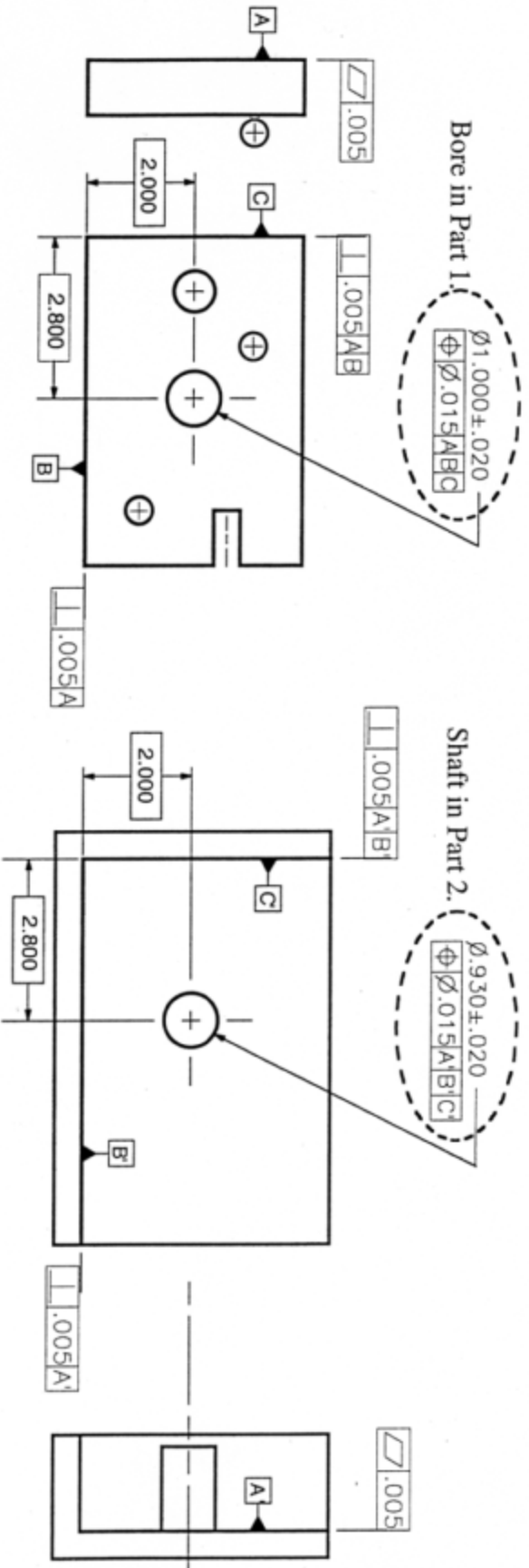


DRF Unification

The governing Concept in Mating Part Design

Unifying DRF (A,B,C) in Part 1, with DRF (A',B',C') in Part 2, by sequentially making their respective Datum Features, ensures that the Bore in Part 1, will accommodate the shaft in Part 2, if both meet their respective tolerances.

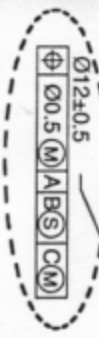
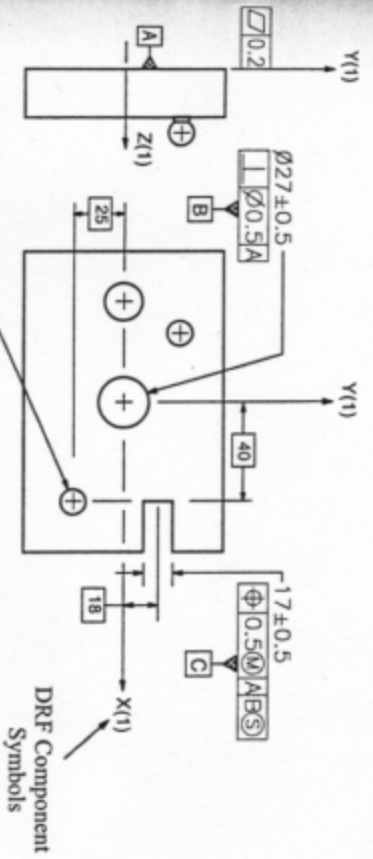
If Part 2, now missing the shaft, is a machining fixture whose DRF (A',B',C') has been united with the coordinate system in a machine tool, then unifying DRF (A,B,C) in Part 1, with DRF (A',B',C') in the machining fixture (Part 2.) ensures that Part 1, is properly oriented and located relative to the machine tool, and that the Bore in Part 1, will be manufactured in the right place.



Beware!

Beware, the shaft as tolerated, cannot be guaranteed to fit inside the hole as tolerated! The designer has overlooked the Datum Reference Frame overlap problem. Since the DRFs in parts 1, and 2, could overlap by as much as .005" in two different directions, the diameter of the bore must be increased, and that of the shaft decreased, by $\sqrt{2} \times .005" = .0071"$ in order to ensure assemblability.

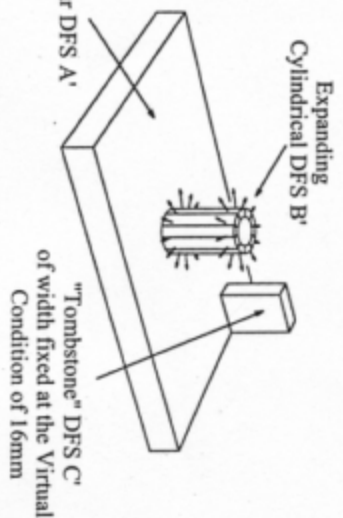
DRF Construction Process Overview



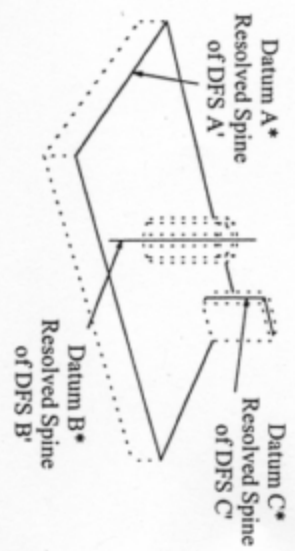
Step 1.
Decode the Feature Control Frame

Step 2.
Identify the Datum Features

Step 3.
Construct the Datum Feature Simulators

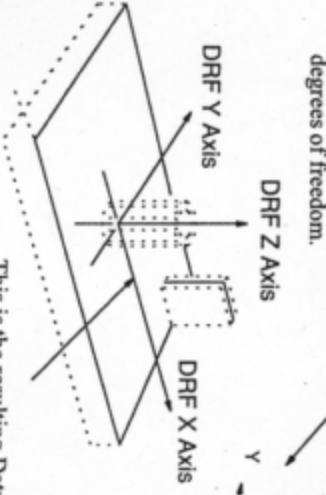


Step 4.
Extract the Datums (Resolved Spines)



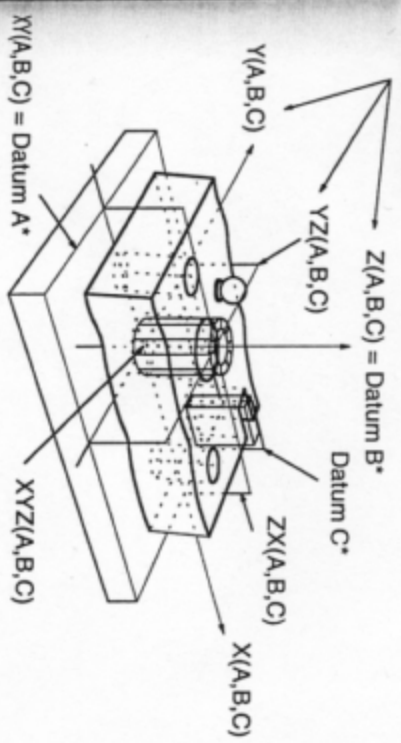
This is the unconstrained Cartesian Coordinate System which Datums A*, B* and C* convert into Datum Reference Frame [A,B(S),C(M)] by sequentially reducing its rotational and translational degrees of freedom.

Step 5.
Construct the DRF in the Simulators



This is the resulting Datum Reference Frame defined by [A,B(S),C(M)].

Step 6.
Make the DRF Manifest in the Actual Part



These are components of the Datum Reference Frame.